

## HYPERBOLA

In the projectiviced affine euclidean space and with respecto the orthonormal coordinate system  $R=\{O; B=\{e_1, e_2\}\}$  we consider the

projective conic  $C$  of equation  $x_1^2 - x_2^2 + 2x_0x_2 - 2x_0x_1 - x_0^2 = 0$ .

```
> restart; with(linalg):with(plots):  
> A:=matrix(3,3,[-1,-1,1,-1,1,0,1,0,-1]);  
A := 
$$\begin{bmatrix} -1 & -1 & 1 \\ -1 & 1 & 0 \\ 1 & 0 & -1 \end{bmatrix}$$
 (1)
```

### Classify.

```
> A00:=submatrix(A,2..3,2..3);  
A00 := 
$$\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$
 (1.1)
```

```
> det(A00); det(A);  
-1  
1 (2)
```

HYPERBOLA.

### Obtain the center, the axes and the asymptotes.

Proper center, pole of the line at infinity.

```
> Center:=evalm(inverse(A)&*matrix(3,1,[1,0,0]));  
Center := 
$$\begin{bmatrix} -1 \\ -1 \\ -1 \end{bmatrix}$$
 (2.1)
```

The asymptotes are the polar lines of the points at infinity of the hyperbola. The hyperbola is the only conic with real asymptotes. They go through the center.

```
> X:=matrix(3,1,[x[0],x[1],x[2]]);  
 (2.2)
```

$$X := \begin{bmatrix} x_0 \\ x_1 \\ x_2 \end{bmatrix} \quad (2.2)$$

$$> \text{conic} := \text{evalm}(\text{transpose}(X) \& * A \& * X)[1,1]; \\ \text{conic} := (-x_0 - x_1 + x_2)x_0 + (-x_0 + x_1)x_1 + (x_0 - x_2)x_2 \quad (2.3)$$

$$> \text{solve}(\{\text{conic}, x[0]=0\}); \\ \{x_0=0, x_1=x_2, x_2=x_2\}, \{x_0=0, x_1=-x_2, x_2=x_2\} \quad (2.4)$$

$$> \text{infil1} := \text{matrix}(3,1,[0,-1,1]); \text{infil2} := \text{matrix}(3,1,[0,1,1]); \\ \text{infil1} := \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} \\ \text{infil2} := \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \quad (2.5)$$

$$> \text{asin1} := \text{evalm}(\text{transpose}(\text{infil1}) \& * A \& * X)[1,1] = 0; \text{asin2} := \text{evalm}(\text{transpose}(\text{infil2}) \& * A \& * X)[1,1] = 0; \\ \text{asin1} := 2x_0 - x_1 - x_2 = 0 \\ \text{asin2} := x_1 - x_2 = 0 \quad (2.6)$$

The axes of the conics with proper center are the lines going through the center and the improper points given by the eigenvectors associated to the distinct eigenvalues of A00.

$$> \text{eigenvectors}(A00); \\ [-1, 1, \{[0 1]\}], [1, 1, \{[1 0]\}] \quad (2.7)$$

$$> \text{v1} := \text{matrix}(3,1,[0,1,0]); \text{v2} := \text{matrix}(3,1,[0,0,1]); \\ \text{v1} := \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \\ \text{v2} := \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \quad (2.8)$$

$$> \text{axis1} := \det(\text{concat}(\text{Center}, \text{v1}, X)) = 0; \text{axis2} := \det(\text{concat}(\text{Center}, \text{v2}, X)) = 0; \\ \text{axis1} := x_0 - x_2 = 0 \\ \text{axis2} := -x_0 + x_1 = 0 \quad (2.9)$$

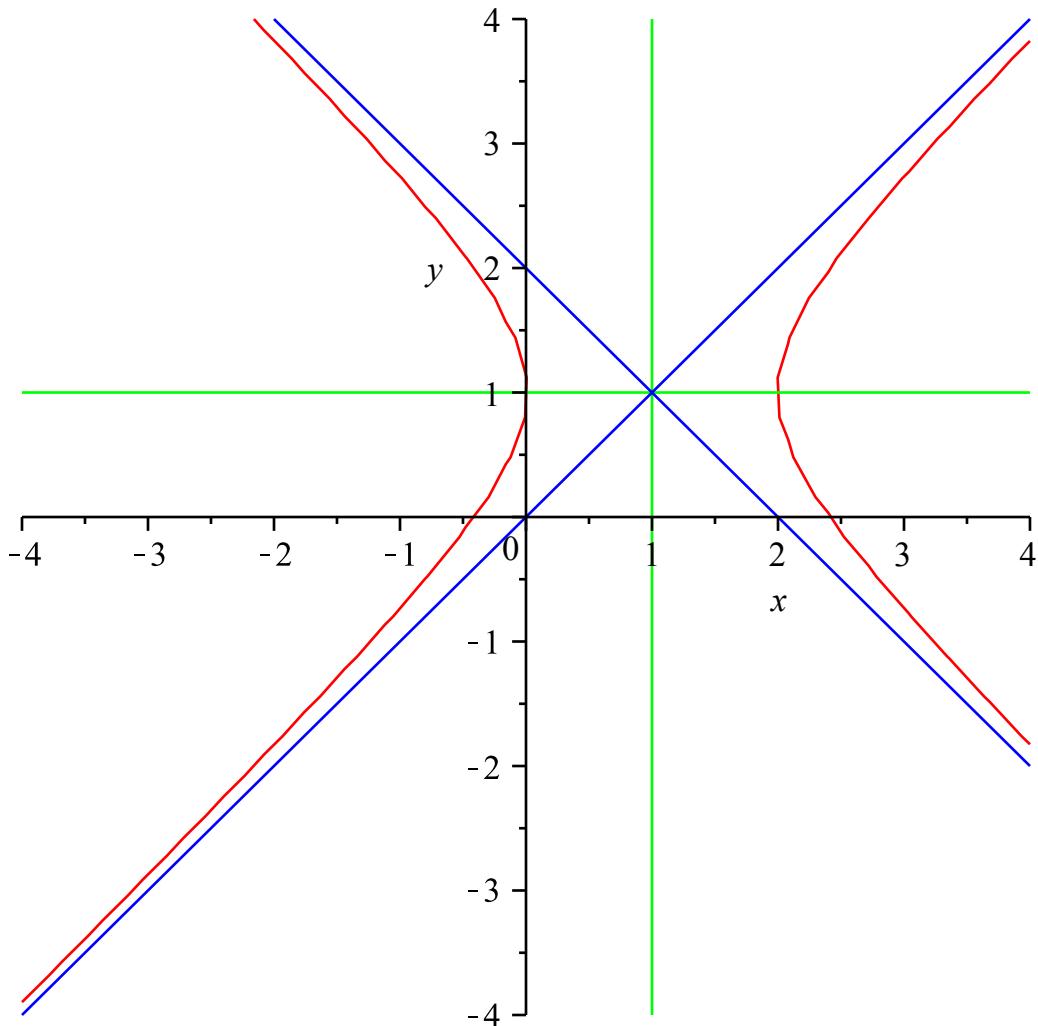
## PLOTTING

```

> Xafin:=matrix(3,1,[1,x,y]):Cafin:=simplify(evalm(transpose
(Xafin)&*A&*Xafin))[1,1];GconicaAfin:=implicitplot({Cafin},x=
-4..4,y=-4..4,color=red,axes=normal):
Cafin := -1 - 2 x + 2 y + x2 - y2                                (2.10)

> GejelAfin:=implicitplot({1-y},x=-4..4,y=-4..4,color=green,
axes=normal):
> Geje2Afin:=implicitplot({-1+x},x=-4..4,y=-4..4,color=green,
axes=normal):
> GasintotalAfin:=implicitplot({x-y},x=-4..4,y=-4..4,color=
blue,axes=normal):
> Gasintota2Afin:=implicitplot({-y-x+2},x=-4..4,y=-4..4,color=
blue,axes=normal):
> display([GconicaAfin,GejelAfin,Geje2Afin, GasintotalAfin,
Gasintota2Afin]);

```



## Invariants, reduced equation in terms of the invariants and coordinate system in which the equation of the conic is the reduced equation.

Invariants:

$$\begin{aligned} > \det(A); \det(A00); \text{eigenvalues}(A00); \\ &\quad 1 \\ &\quad -1 \\ &\quad 1, -1 \end{aligned} \tag{3.1}$$

$$\begin{aligned} > \lambda[1]:=1; \lambda[2]:=-1; \\ &\quad \lambda_1 := 1 \\ &\quad \lambda_2 := -1 \end{aligned} \tag{3.2}$$

Reduced equation in terms of invariants:

$$\begin{aligned} > \lambda[1]*x^2 + \lambda[2]*y^2 + \det(A)/\det(A00) = 0; \\ &\quad x^2 - y^2 - 1 = 0 \end{aligned} \tag{3.3}$$

The new coordinate system  $R'=\{O', B'\}$  has:

- origin  $O'$  the center of the conic [1,1].
- basis  $B'$  an orthonormal basis given by the eigenvectors of  $A00$ .

$$\begin{aligned} > Q := \text{matrix}(3, 3, [1, 0, 0, 1, 1, 0, 1, 0, 1]); \\ &\quad Q := \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \end{aligned} \tag{3.4}$$

$$\begin{aligned} > Ap := \text{evalm}(\text{transpose}(Q) * A * Q); Xa := \text{matrix}(3, 1, [1, x, y]); \\ &\quad Ap := \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \\ &\quad Xa := \begin{bmatrix} 1 \\ x \\ y \end{bmatrix} \end{aligned} \tag{3.5}$$

$$\begin{aligned} > \text{reduced} := \text{simplify}(\text{evalm}(\text{transpose}(Xa) * Ap * Xa)[1, 1]); \\ &\quad \text{reduced} := x^2 - y^2 - 1 \end{aligned} \tag{3.6}$$