

Feeding Networks

Basic Concepts, Principal Devices

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Outline

Introduction
Transmission Lines Architecture
Some Feeding Devices

A printed line Consists of:

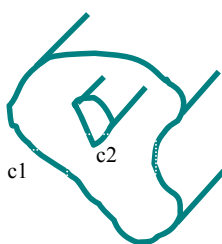
Line :

- Metallic surface
- Extremely thin surface (thickness: 10 – 50μm ⇒ typical: 18μm y 35μm)

Substrate :

- Dielectric layer. Thickness: 0.003λ - 0.05λ
- Dielectric Constants within the range: 1 ≤ ε_r ≤ 12

Ground plane.



TEM Mode

$$\vec{E}_t(u_1, u_2, z) = (-\nabla\phi)e^{-\gamma_0 z}$$

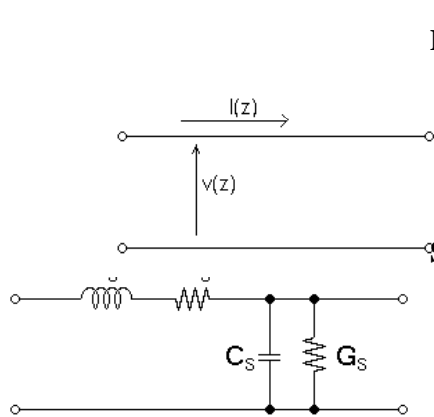
$$\vec{H}_t(u_1, u_2, z) = \frac{\hat{z} \wedge (-\nabla\phi)e^{-\gamma_0 z}}{\eta}$$

$$\int_{c1}^{c2} \nabla\phi e^{-\gamma_0 z} \cdot d\vec{l} = V(z) \leftarrow \text{POTENTIAL WAVE}$$

$$I(z) = \int_{c2} j_s dl = \int_{c2} \hat{n}_s \wedge \hat{H}_t dl = \int_{c2} \frac{-\nabla\phi \cdot \hat{n}_s}{\eta} e^{-\gamma_0 z} dl$$

↑
CURRENT WAVE

Transmission line model:



Primary Parameters :

$$Z = \frac{V(z)}{I(z)} = \eta \frac{\int_{c1}^{c2} \nabla\phi e^{-\gamma_0 z} \cdot d\vec{l}}{\int_{c2} \frac{-\nabla\phi \cdot \hat{n}_s}{\eta} e^{-\gamma_0 z} d\vec{l}} = \eta \cdot k_g$$

Characteristic Impedance (pointing to η) and Geometric Constant (pointing to k_g)

$$\gamma = \omega\sqrt{\mu\epsilon}$$

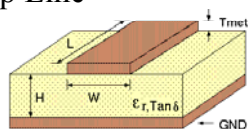
Secondary Parameters :

$$C_s = \frac{\epsilon}{k_g} \quad L_s = k_g \mu \quad G_s = \omega C_g \delta$$

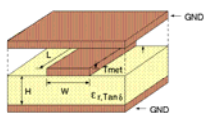
Introduction
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Basic Models

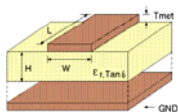
➤ Microstrip Line



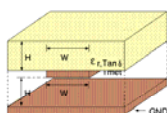
➤ Covered microstrip line



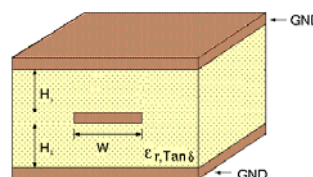
➤ Suspended microstrip line



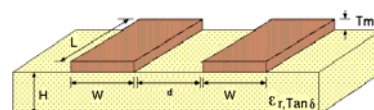
➤ Inverted microstrip line



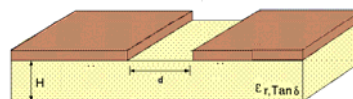
➤ Stripline



➤ Coplanar



➤ Slot



- Basic Features:
 - Line width w
 - Line thickness t
 - Line losses α_c
 - Substrate thickness h
 - Substrate dielectric constant ϵ_r
 - Substrate losses: loss tangent $\tan(\delta)$
 - Radiation losses α_r
- Main parameters:
 - Characteristic impedance Z
 - Effective dielectric Constant ϵ_{eff}

[1] B. C. Wadell, "Transmission Line Design Handbook", Artech House, London, 1991

- Phase velocity v_p :
$$v_p = \frac{c_0}{\sqrt{\mu_r \epsilon_r}}$$
- Layer Wavelength λ_g :
$$\lambda_g = \frac{\lambda_0}{\sqrt{\mu_r \epsilon_r}}$$

Non-homogeneous dielectric:

$$\lambda_g = \frac{\lambda_0}{\sqrt{\epsilon_{eff}}} \quad v_{p_g} = \frac{c_0}{\sqrt{\epsilon_{eff}}}$$

- Non-homogeneous dielectrics: when we have several dielectric layers (multilayer structure) or even when ϵ_r , μ_r change, depending on the dielectric layer position.
- The effective dielectric layer ϵ_{eff} takes into account the wave propagation inside non-homogeneous dielectric layers.

⇒ We have to Adopt a compromise solution

Layer thickness h

- Reduce surface wave losses ⇒ $h \searrow$
- Increase bandwidth ⇒ $h \nearrow$

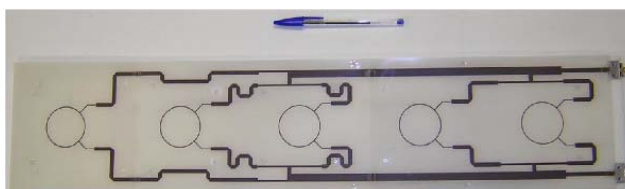
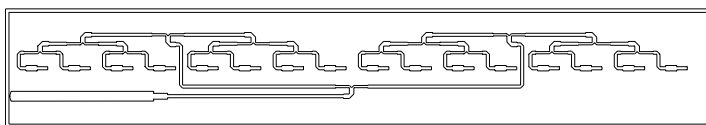
Substrate dielectric constant ϵ_r

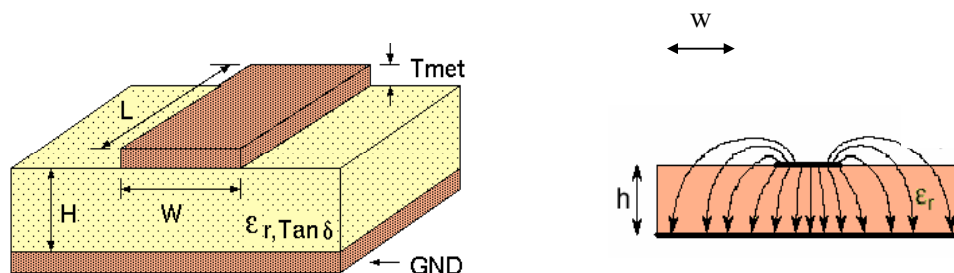
- Tiny structures ⇒ $\epsilon_r \nearrow$

Line width w

- $w \ll \lambda_g/2$
- Decrease undesired line radiation ⇒ $w \ll \lambda_g/2$

- Feeding network:
 - For antennas
- Printed circuits:
 - Filters
 - Dividers
 - Mixers
 - ...





- The most common transmission structure for planar antennas.
- The main working mode is quasi-TEM \Rightarrow almost all the field is concentrated inside the substrate.
- To avoid surface waves \rightarrow electrically thin substrate ($0.003\lambda < h < 0.05 \lambda$)
- Dielectric constant ϵ_r : $2.2 < \epsilon_r < 12$.

•Features:

➤ Characteristic line impedance Z : $\Rightarrow 0.05 \leq w/h \leq 100, \epsilon_r \leq 16 \Rightarrow 0.2\% \text{ error}$

$$Z = \frac{\eta_0}{\sqrt{\epsilon_{eff}}} K_g = \frac{\sqrt{\frac{\mu_0}{\epsilon_0}}}{2\pi\sqrt{\epsilon_{eff}}} \ln \left(\frac{6 + (2\pi - 6) \cdot e^{\left(-\left(\frac{30.666 \cdot h}{w}\right)^{0.7528}\right)} \cdot h}{w} + \sqrt{1 + \frac{4 \cdot h^2}{w^2}} \right)$$

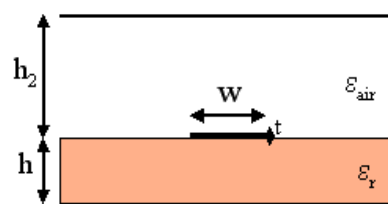
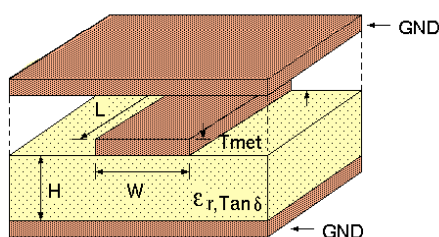
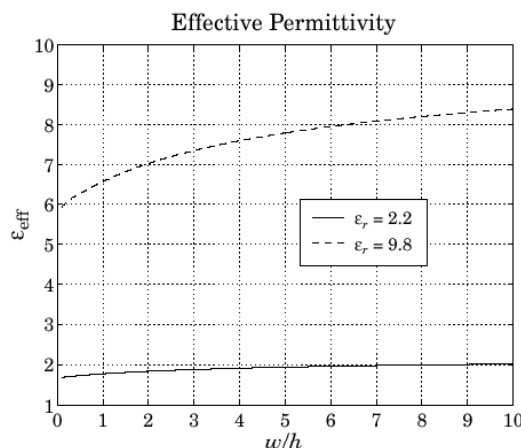
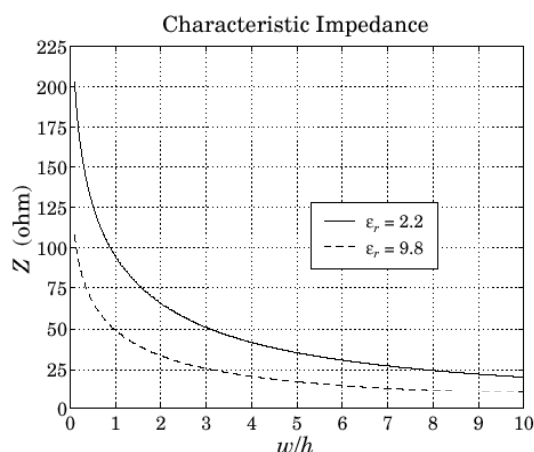
Effective dielectric constant ϵ_{eff} : $\Rightarrow \epsilon_r \leq 16, 0.05 \leq w/h \leq 20 \Rightarrow 1\% \text{ error}$

$$\epsilon_{eff} = \frac{\epsilon_r + 1}{2} + \frac{\epsilon_r - 1}{2} \left[\left(1 + \frac{12 \cdot h}{w}\right)^{-\frac{1}{2}} + 0.04 \left(1 + \frac{w}{h}\right)^2 \right] \quad w/h < 1$$

$$\epsilon_{eff} = \frac{\epsilon_r + 1}{2} + \frac{\epsilon_r - 1}{2} \left(1 + \frac{12 \cdot h}{w}\right)^{-\frac{1}{2}} \quad w/h \geq 1$$

- $< 2\%$ error considering $\epsilon_r > 16$
- $< 2\%$ error considering $\frac{w}{h} < 0.05$

- Typical dielectric substrates used to perform microstrip lines are:
 - RT-Duroid 5880 $\epsilon_r = 2.2$
 - Alumina (ceramic, Al_2O_4 (97%)) $\epsilon_r = 9.8$
- Real prototype width/thickness values within the range $0.1 \leq \frac{w}{h} \leq 10$
- Real prototype characteristic impedance in the range $10 \leq Z \leq 200$ ohms



- Considering the same dimensions as in a conventional microstrip, the covered microstrip line has a lower impedance, due to the existence of a new ground plane.
- For the same impedance Z (as in the conventional microstrip) \Rightarrow the line width is smaller.
- The effective dielectric constant ϵ_{eff} for the same dimensions (as in conventional microstrip) is lower.
- When $h_2 \nearrow \Rightarrow$ microstrip line
- When $h_2 \searrow \Rightarrow Z \searrow \vee \epsilon_{eff} \searrow$

•Features :

➤ Characteristic impedance Z :

$$Z = \frac{\eta_0}{\sqrt{\epsilon_{eff}}} K_g = \frac{\sqrt{\frac{\mu_0}{\epsilon_0}}}{2\pi\sqrt{\epsilon_{eff}}} \ln \left[\underbrace{\frac{6 + (2\pi - 6) \cdot e^{\left(-\left(\frac{30.666 \cdot h}{w}\right)^{0.7528}\right)} \cdot h}{w} + \sqrt{1 + \frac{4 \cdot h^2}{w^2}}}_{Z^{line microstrip}} \right] - \frac{\Delta Z}{\sqrt{\epsilon_{eff}}}$$

$$\Delta Z = \left[270 \left[1 - \tanh \left(1.192 + 0.706 \sqrt{1 - \frac{h_2}{h}} - \frac{1.389}{1 + \frac{h_2}{h}} \right) \right] \right] \cdot 1.0109 - \tanh^{-1} \left(\frac{0.012 \frac{w}{h} + 0.177 \left(\frac{w}{h}\right)^2 - 0.027 \left(\frac{w}{h}\right)^3}{\left(1 + \frac{h_2}{h}\right)^2} \right)$$

⇒ ±0.1% error, 0.1 ≤ w/h ≤ 6; ⇒ ±0.2% error, 6 ≤ w/h ≤ 10

[1] B. C. Wadell, "Transmission Line Design Handbook", Artech House, London, 1991.

➤ Effective dielectric constant ϵ_{eff} :

$$\epsilon_{eff} = \frac{\epsilon_r + 1}{2} + \alpha \frac{\epsilon_r - 1}{2}$$

–It depends on the superior metallic plane distance, and the line width:

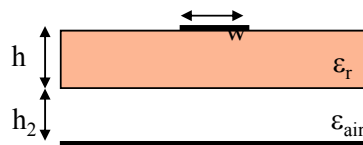
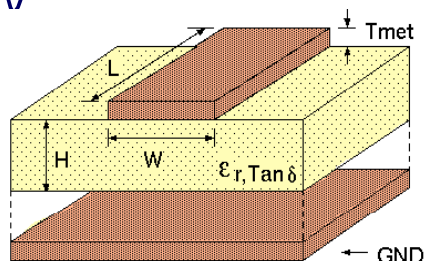
$$\alpha = \tanh \left(1.043 + 0.121 \frac{h_2}{h} - \frac{1.164h}{h_2} \right) \left(\left(1 + \frac{10h}{w} \right)^{ab} - \left(\frac{2t \ln(2)}{\pi h \sqrt{\frac{w}{h}}} \right) \right)$$

where:

$$a = 1 + \frac{1}{49} \ln \left(\frac{\left(\frac{w}{h}\right)^2 \left[\left(\frac{w}{h}\right)^2 + \left(\frac{1}{52}\right)^2 \right]}{\left(\frac{w}{h}\right)^4 + 0.432} \right) + \frac{1}{18.7} \ln \left(1 + \left(\frac{w}{18.1h}\right)^3 \right) \quad b = -0.564 \left(\frac{\epsilon_r - 0.9}{\epsilon_r + 3} \right)^{0.053}$$

⇒ ±0.2% error, 0.01 ≤ w/h ≤ 100 y 1 ≤ ϵ_r ≤ 100 :

[1] B.C. Wadell, "Transmission Line Design Handbook", Artech House, London, 1991.



- The suspended microstrip line is used when low losses are needed.
- The effective dielectric constant ϵ_{eff} is reduced. For the same width (as in microstrip line) $\Rightarrow Z$ is higher.
- For the same impedance (as in microstrip line) \Rightarrow the line is wider.
- When $h_2 \searrow \Rightarrow$ microstrip line
- When $h_2 \nearrow \Rightarrow Z \nearrow \epsilon_{eff} \searrow$

[1] B. C. Wadell, "Transmission Line Design Handbook", Artech House, London, 1991.

• Features:

➤ Characteristic impedance Z : $\Rightarrow \pm 0.2\%$ error, $\epsilon_r \leq 20$

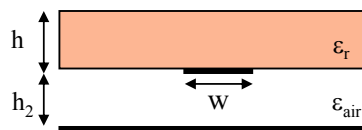
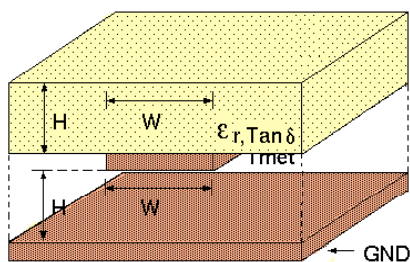
$$Z = \frac{\eta_0}{\sqrt{\epsilon_{eff}}} K_g = \frac{\sqrt{\mu_0}}{2\pi\sqrt{\epsilon_{eff}}} \ln \left(\frac{6 + (2\pi - 6) \cdot e^{\left(-\left(\frac{30.666}{u}\right)^{0.7528}\right)}}{u} + \sqrt{1 + \frac{4}{u^2}} \right) \quad u = \frac{w}{h + h_2}$$

Effective dielectric constant ϵ_{eff} : $\Rightarrow \pm 0.2\%$ error, $\epsilon_r \leq 20$

$$\epsilon_{eff} = \frac{1}{\left[1 + \frac{h}{h_2} \left(h' - h'' \ln \left(\frac{w}{h_2} \right) \right) \left(\frac{1}{\sqrt{\epsilon_r}} - 1 \right) \right]^2} \quad h' = \left(0.8621 - 0.1251 \ln \left(\frac{h}{h_2} \right) \right)^4$$

$$h'' = \left(0.4986 - 0.1397 \ln \left(\frac{h}{h_2} \right) \right)^4$$

[1] B. C. Wadell, "Transmission Line Design Handbook", Artech House, London, 1991.



- The inverted microstrip line is also used when low losses are desired.
- Effective dielectric constant ϵ_{eff} is reduced. For the same width (as in conventional microstrip line) $\Rightarrow Z$ is higher.
- For the same impedance Z (as in conventional microstrip) \Rightarrow the line is wider.
- When $h_2 \searrow \Rightarrow$ microstrip line
- When $h_2 \nearrow \Rightarrow Z \nearrow$ y $\epsilon_{eff} \searrow$ ($\epsilon_{eff} \approx 1$, Air)

[1] B. C. Wadell, "Transmission Line Design Handbook", Artech House, London, 1991.

• Features:

➤ Characteristic impedance Z : $\Rightarrow \pm 1\%$ error, $\epsilon_r \leq 20$

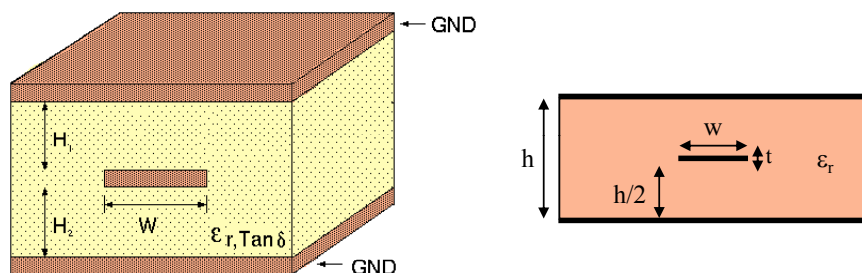
$$Z = \frac{\eta_0}{\sqrt{\epsilon_{eff}}} K_g = \frac{\sqrt{\frac{\mu_0}{\epsilon_0}}}{2\pi\sqrt{\epsilon_{eff}}} \ln \left[\frac{6 + (2\pi - 6) \cdot e^{\left(-\left(\frac{30.666}{u}\right)^{0.7528}\right)}}{u} + \sqrt{1 + \frac{4}{u^2}} \right] \quad u = \frac{w}{h_2}$$

➤ Effective dielectric constant ϵ_{eff} : $\Rightarrow < 0.6\%$ error, $\epsilon_r \leq 20$; $0.5 \leq w/h_2 \leq 10$ y $0.06 \leq h/h_2 \leq 1.5$

$$\epsilon_{eff} = \left[1 + \frac{h}{h_2} \left(h' - h'' \ln \left(\frac{w}{h_2} \right) \right) (\sqrt{\epsilon_r} - 1) \right]^2 \quad h' = \left(0.5173 - 0.1515 \ln \left(\frac{h}{h_2} \right) \right)^2$$

$$h'' = \left(0.3092 - 0.1047 \ln \left(\frac{h}{h_2} \right) \right)^2$$

[1] B. C. Wadell, "Transmission Line Design Handbook", Artech House, London, 1991.



- For the same width, ϵ_r and $h/2 = h_{\text{microstrip}}$ as in conventional microstrip line $\Rightarrow Z$ is lower.
- For the same impedance as in conventional microstrip line (same ϵ_r and $h/2 = h_{\text{microstrip}}$) \Rightarrow the line is narrower.

• Features:

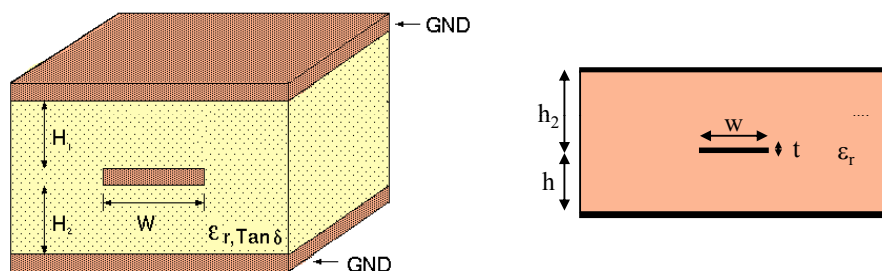
➤ Characteristic impedance Z : \Rightarrow 0.5% error, $\epsilon_r \leq 20$ y $w/h > 0.1$

$$Z = \frac{\eta_0}{\sqrt{\epsilon_{\text{eff}}}} K_g = \frac{\sqrt{\frac{\mu_0}{\epsilon_0}}}{2\pi\sqrt{\epsilon_r}} \ln \left(1 + 0.5 \frac{8h}{\pi w'} \left[\frac{8h}{\pi w'} + \sqrt{\left(\frac{8h}{\pi w'} \right)^2 + 6.27} \right] \right)$$

$$w' = w + \frac{\Delta w}{t} \quad \frac{\Delta w}{t} = \frac{\ln\left(\frac{5h}{t}\right)}{3.2}$$

➤ Effective dielectric impedance ϵ_{eff} :

$$\epsilon_{\text{eff}} = \epsilon_r$$



- For the same dimensions (as symmetric stripline) $\Rightarrow Z$ is lower.
- For the same impedance \Rightarrow the width is lower.

[1] B. C. Wadell, "Transmission Line Design Handbook", Artech House, London, 1991.

• Features:

- Characteristic impedance Z : \Rightarrow 0.5% error, $\epsilon_r \leq 20$ y $w'/h > 0.1$

$$Z = \frac{\eta_0}{\sqrt{\epsilon_{eff}}} K_g = \frac{1}{\sqrt{\epsilon_r}} \left(\frac{\sqrt{\mu_0}}{2\pi\sqrt{\epsilon_r}} \ln \left[1 + 0.5 \frac{8h}{\pi w'} \left[\frac{8h}{\pi w'} + \sqrt{\left(\frac{8h}{\pi w'}\right)^2 + 6.27} \right] \right] \right) - \Delta Z$$

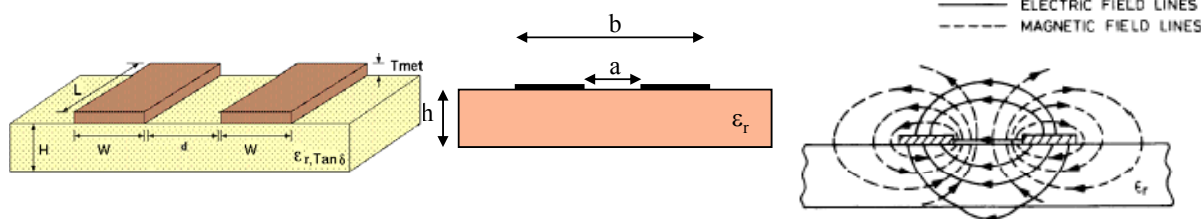
$Z_{symmetric}(\epsilon_r, w, h, t)$

$$\Delta Z = \frac{0.26\pi}{8} Z'^2 \left(0.5 - \frac{h_2 + \frac{t}{2}}{h_2 + h + t} \right)^{2.2} \left(\frac{t+w}{h_2 + h + t} \right)^{2.9} \quad Z'' = 2 \left[\frac{Z_{symmetric}(\epsilon_r, w, h_2, t) Z_{symmetric}(\epsilon_r, w, h, t)}{Z_{symmetric}(\epsilon_r, w, h_2, t) + Z_{symmetric}(\epsilon_r, w, h, t)} \right]$$

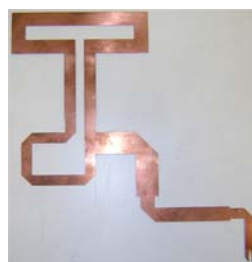
- Effective dielectric constant ϵ_{eff} :

$$\epsilon_{eff} = \epsilon_r$$

[1] B. C. Wadell, "Transmission Line Design Handbook", Artech House, London, 1991.



- There is no ground plane.
- In order to prevent superior mode propagation: $b < \lambda_g$
- Practical example: couplers, dipole feeding...



[1] B. C. Wadell, "Transmission Line Design Handbook", Artech House, London, 1991.

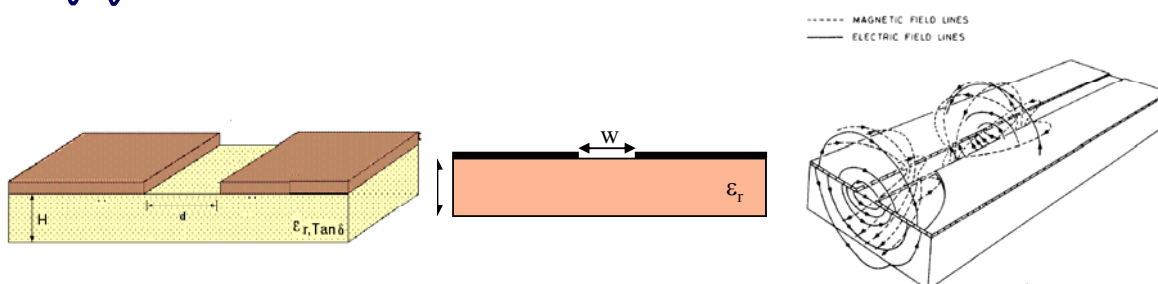
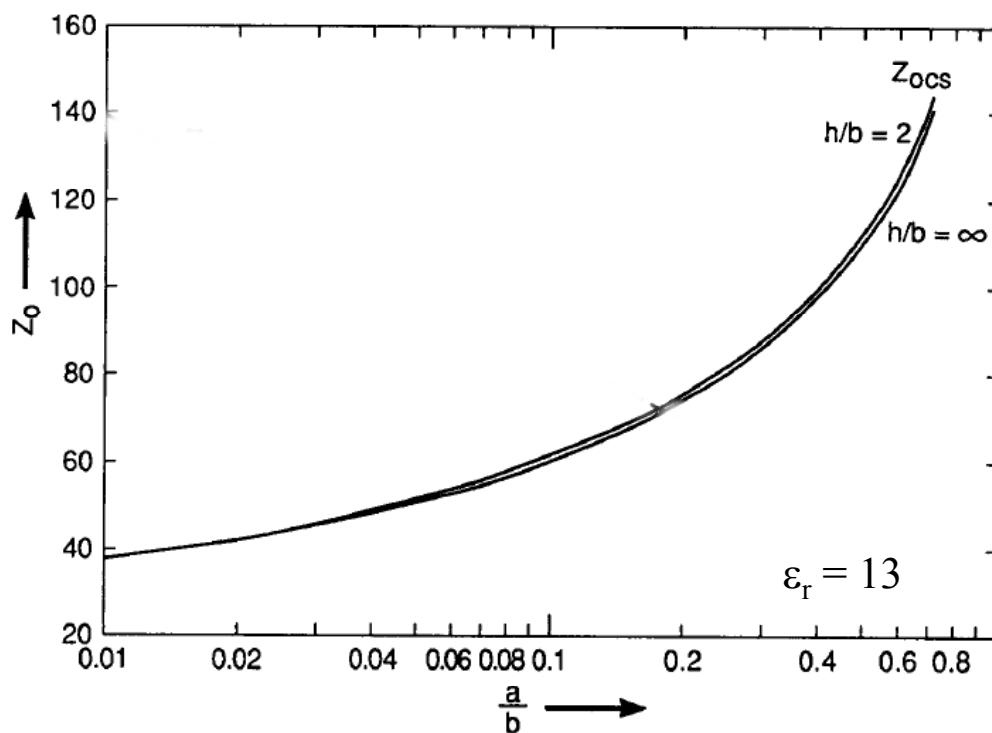
- Features:
 - Characteristic impedance Z : 2% error,

$$Z = \frac{\eta_0}{\sqrt{\epsilon_{eff}}} K_g = \frac{\sqrt{\frac{\mu_0}{\epsilon_0}}}{\sqrt{\epsilon_{eff}}} \frac{1}{2\pi} \ln \left(2 \frac{\sqrt{1 + \frac{a}{b}} + \sqrt[4]{4 \frac{a}{b}}}{\sqrt{1 + \frac{a}{b}} - \sqrt[4]{4 \frac{a}{b}}} \right)$$

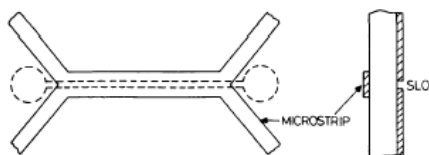
- Effective dielectric constant ϵ_{eff} : 1% error

$$\epsilon_{eff} = 1 + \frac{\epsilon_r - 1}{2} \ln \left(2 \left(\frac{\sqrt{1 + k_1} + \sqrt[4]{4k_1}}{\sqrt{1 + k_1} - \sqrt[4]{4k_1}} - \frac{\sqrt{1 + \frac{a}{b}} + \sqrt[4]{4 \frac{a}{b}}}{\sqrt{1 + \frac{a}{b}} - \sqrt[4]{4 \frac{a}{b}}} \right) \right) \quad k_1 = \frac{\sinh\left(\frac{\pi a}{4h}\right)}{\sinh\left(\frac{\pi b}{4h}\right)}$$

[1] B. C. Wadell, "Transmission Line Design Handbook", Artech House, London, 1991.



- The slot line is a TE structure, not a TEM one.
- This structure needs a substrate with a high dielectric constant value ϵ_r ($\epsilon_r \geq 10$) \Rightarrow on behalf to concentrate propagating fields and decrease radiation.
- The slot line is combined with microstrip in designing directional couplers, branchlines...



[1] B. C. Wadell, "Transmission Line Design Handbook", Artech House, London, 1991.

• **Features:**

➤ Characteristic impedance Z : \Rightarrow 2% error, $0.02 \leq w/h \leq 1$

$$Z = 72.62 - 81.028 \ln(\epsilon_r) + \frac{50 \left(\frac{w}{h} - 0.02 \right) \left(\frac{w}{h} - 0.1 \right)}{\frac{w}{h}} + 2.3026 \ln \left(\frac{w}{h} 100 \right) \left(44.28 - 45.0849 \ln(\epsilon_r) \right) - \left[0.7368 \ln(\epsilon_r) - 0.11 + \frac{w}{h} (2.4638 \ln(\epsilon_r) + 1.44) \right] \cdot \left(11.4 - 13.9768 \ln(\epsilon_r) - \frac{h}{\lambda_g 100} \right)^2$$

➤ Effective dielectric constant ϵ_{eff} : \Rightarrow 2% error, $0.02 \leq w/h \leq 1$

$$\epsilon_{eff} = \left[0.923 - 1.0316 \ln(\epsilon_r) + 0.2 \frac{w}{h} - \left(0.6678 \frac{w}{h} + 0.1082 \right) \ln \left(\frac{h}{\lambda_0 100} \right) \right]^{-2}$$

[1] B. C. Wadell, "Transmission Line Design Handbook", Artech House, London, 1991.

Typical losses for different lines

Typical losses with those structures when applying high frequency (10 GHz)

Network	Losses (dB/m)
Waveguide	0.2
Suspended line	1.8 - 3.0
Stripline	2.7 - 5.6
Microstrip line	4 - 6

Printed lines at high frequency need quality materials \Rightarrow loss tangent : $\tan(\delta) < 0.002$

Features of substrates for printed lines at 10 GHz		
	Dielectric constant: ϵ_r	losses: $\tan(\delta)$
Epoxy fiberglass FR-4	4.4	0.01
Laminex	4.8	0.03
Taconic	2.33	0.0009
Kapton	3.5	0.002
CuClad	2.17	0.0009
RT Duroid 5880 (teflon + glass fiber)	2.2	0.0009
Alumina (Ceramic form of Al_2O_3)	9.9	0.0003
RT Duroid 6010 (PTFE ¹ ceramic)	10.5	0.002
GaAs (Gallium Arsenide) (Semiconductor dielectric)	12.8	0.0006

¹ Polytetrafluoroethylene (Teflon)

	Substrate thickness	ϵ_r
Reduction in line radiation	Quite little	high
Small dimensions	little	high
Low Losses	little	low
Reduction in losses due to surface currents	little	low
Increase in band width	big	low

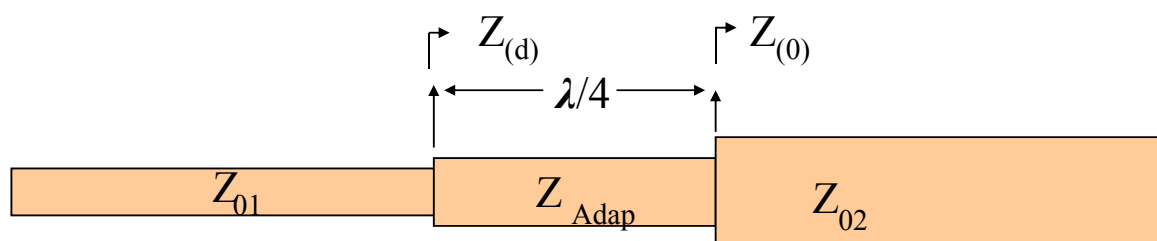


➤ Thin substrates with high ϵ_r are used in microwave circuitry, as feeding network:

- Advantages:
 - Lower line width.
 - Reduction in radiation and coupling effects, although they should not be neglected.
- Disadvantaged:
 - Higher losses.
 - Lower efficiency.
 - Lower bandwidth.

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Some Feeding Devices

$\lambda/4$ Adaptator



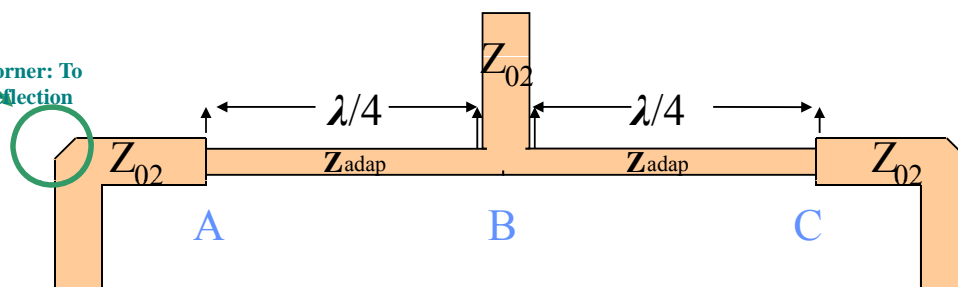
Transformation (considering no losses):

$$Z(d) = Z_{adap} \frac{Z(0) \cos \beta d + Z_{adap} j \sin \beta d}{Z_{adap} \cos \beta d + Z(0) j \sin \beta d}$$

$\lambda/4$ case

$$Z(d) = Z_{adap} \frac{Z(0) \cos \frac{\pi}{2} + Z_{adap} j \sin \frac{\pi}{2}}{Z_{adap} \cos \frac{\pi}{2} + Z(0) j \sin \frac{\pi}{2}} = Z_{adap} \frac{Z_{adap}}{Z(0)} \rightarrow \boxed{Z_{adap} = \sqrt{Z(0)Z(d)}} \left\{ \begin{array}{l} Z(0) = Z_{02} \\ Z(d) = Z_{01}^* = Z_{01} \end{array} \right.$$

Bended Corner: To prevent reflection



Point A: $Z(A) = Z_{02}$

Point C: $Z(C) = Z_{02}$

Point B:

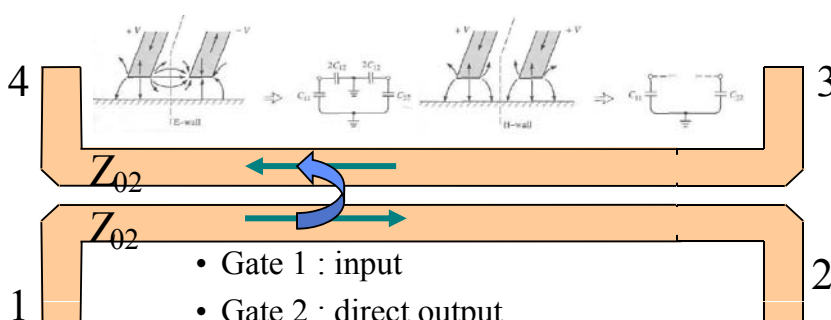
$$Z(B) = Z(B_{izq}) // Z(B_{der}) = \frac{Z(B_{izq}) \cdot Z(B_{der})}{Z(B_{izq}) + Z(B_{der})}$$

$$Z(B) = Z_{02}$$

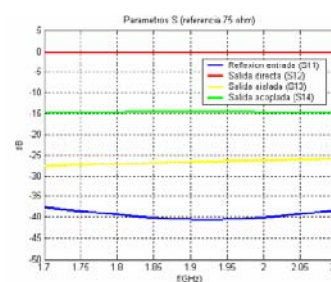
$$Z(B_{izq}) = Z(B_{der}) = \frac{Z_{adapt}^2}{Z_{02}}$$

$$Z_{02} = \frac{\frac{Z_{adapt}^2}{Z_{02}} \cdot \frac{Z_{adapt}^2}{Z_{02}}}{\frac{Z_{adapt}^2}{Z_{02}} + \frac{Z_{adapt}^2}{Z_{02}}} = \frac{Z_{adapt}^2}{2Z_{02}}$$

$$Z_{adapt} = \sqrt{2}Z_{02}$$

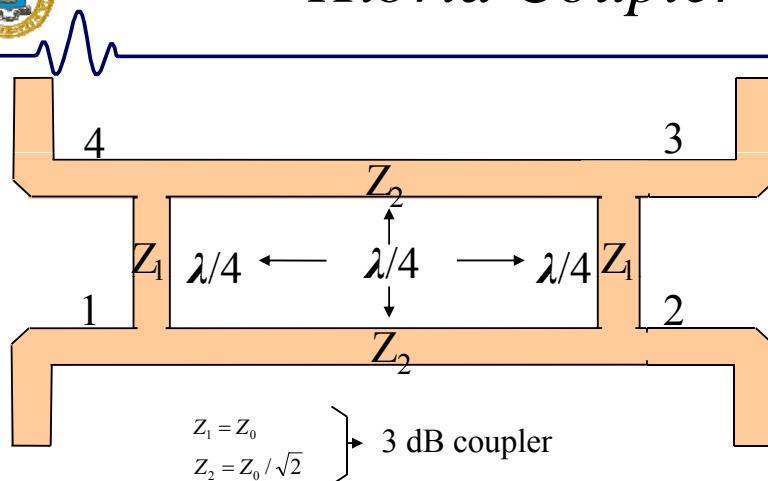


- Gate 1 : input
- Gate 2 : direct output
- Gate 3 : isolated output
- Gate 4 : coupled output



- A portion of the injected power (**input**) yields coupling in the alongside line (**coupled output**), the rest flows through the **coupled output**.
- Power relation between direct and coupled output is a designer choice.
- Direct and coupled outputs have a signal phase delay (90°).
- Ideally, there is no power at the isolated gate.

Hibrid Coupler 90°

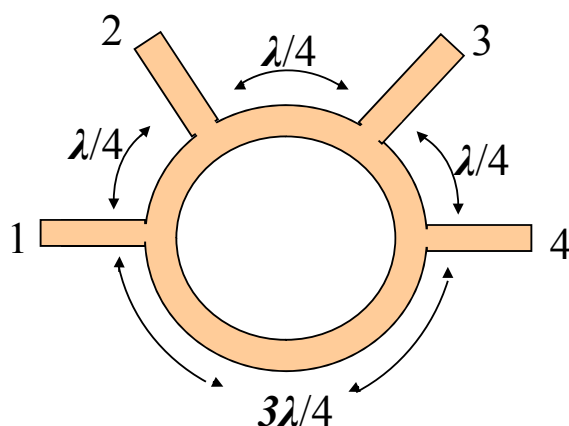


- Gate 1 : input
- Gate 2 : -90° output
- Gate 3 : -180° output
- Gate 4 : isolated port

$$S = \frac{1}{\sqrt{2}} \begin{bmatrix} 0 & -j & -1 & 0 \\ -j & 0 & 0 & -1 \\ -1 & 0 & 0 & -j \\ 0 & -1 & -j & 0 \end{bmatrix}$$

- A portion of the injected power (1) reaches 3 with -180° phase delay), the rest flows through the -90° output (2).
- The output signals at 2 and 3 have a 90° phase delay, referred one to the other.
- Ideally, there is no power at the isolated gate (4).

Circular Coupler (Rat Race)



- Gate 1 : input
- Gate 2 : output -90°
- Gate 3 : isolated port
- Gate 4 : output -270°

$$S = \frac{1}{\sqrt{2}} \begin{bmatrix} 0 & -j & 0 & j \\ -j & 0 & -j & 0 \\ 0 & -j & 0 & -j \\ j & 0 & -j & 0 \end{bmatrix}$$

- The injected power at 1 reaches 2 and 4 with a phase delay of -/+90° respectively.
- The output signals at 2 and 4 have a 180° phase delay, referred one to the other.
- Ideally, there is no power at the isolated gate (3).

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